

Diversity Coloring for Information Storage in Networks

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Abstract — We propose a new file placement scheme using MDS codes, and formulate it as the Diversity Coloring Problem. We then present an optimal diversity coloring algorithm for trees.

I. INTRODUCTION

Storing multiple copies of a widely shared file on a network, compared to storing just a single copy, reduces communication costs for file retrieving and improves fault-tolerance [1]. Performance and reliability can be further improved by introducing parity-check information. Some pioneering work on it has been done by Naor and Roth in [3].

If we split a file into K equally long segments, and encode them using an (N, K) MDS code to generate N segments, then the file can be reconstructed by decoding any K of those N segments. We propose the following file placement scheme for a network: store one segment on each node of the network in such a way that every node can reconstruct the file by retrieving and decoding the segments stored within m hops. If we represent the N segments with N different colors, then the file placement scheme can be formulated as the following coloring problem which we call the ‘Diversity Coloring Problem’:

Diversity Coloring Problem: Given a graph and N colors, how to assign one color to each vertex, (different vertices can have the same color), such that for every vertex, there are at least K different colors within m hops? (A coloring that satisfies the above condition is called a diversity coloring. And fixing the parameters K and m and the graph, a diversity coloring is called *optimal* if it uses the smallest parameter N .)

II. DIVERSITY COLORING ON TREES

We can prove the following result:

Theorem 1 Given a tree $G(V, E)$ and parameters N , K and m ($N \geq K$), there exists a diversity coloring on the tree if and only if for every vertex $v \in V$, there are at least K vertices within m hops from v (including v itself).

Before we present the diversity coloring algorithm for trees, let’s define some terms. Given a tree $G(V, E)$, we use v_0 to denote its root. For any two vertices $u \in V$ and $v \in V$, $d(u, v)$ denotes the number of edges in the unique path connecting u and v (that is, u is $d(u, v)$ hops away from v). For any vertex $v \in V$, we say v is at level $d(v, v_0)$. A vertex u is called a ‘quasi-descendant of v ’ if and only if $u = v$ or u is a descendant of v .

The following is the diversity coloring algorithm for trees.

Algorithm: Diversity Coloring on Tree $G(V, E)$

Input: A tree $G(V, E)$, parameters N , K and m ($N \geq K$).

Output: A diversity coloring on $G(V, E)$.

Prerequisite: $\forall v \in V$, there are at least K vertices within m hops from v (including v itself).

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Algorithm:

1. Let $R = \{v_0\}$.

2. while $R \neq \emptyset$ do

{ Arbitrarily select a vertex $v \in R$. Let $R \leftarrow R - \{v\}$.

Inspect the following vertices in order: v , a (any) descendant of v at level $d(v, v_0) + 1$, a (any) descendant of v at level $d(v, v_0) + 2, \dots$. Stop the inspection as soon as such a vertex w is found—there are less than K different colors within m hops from w . Let C denote the set of colors that are not within m hops from w . Use colors in C to color quasi-descendants of v that haven’t yet been colored in the following way: use each color in C at most once; always color vertices at a smaller level before coloring vertices at a greater level; keep coloring until all colors in C are used or until there is no uncolored quasi-descendant of v left.

Let S denote the set of vertices that satisfies the following two conditions: (1) $\forall u \in S$, u is a quasi-descendant of v ; (2) $\forall u \in S$, u has at least one quasi-descendant for which there are less than K different colors within m hops, and u has at least one uncolored quasi-descendant; if we use a to denote a quasi-descendant of u at the smallest level for which there are less than K different colors within m hops, and use b to denote an uncolored quasi-descendant of u at the smallest level, then $d(a, u) + d(b, u) \leq m$.

Let $R \leftarrow R + \{x | x \in S; \text{no ancestor of } x \text{ is in } S.\}$

}

3. Arbitrarily color the remaining uncolored vertices.

□

It can be shown that given the distance matrix, the above algorithm can be carried out with time complexity $O(K|V| + m|V|)$.

By letting $N = K$, we can always use the above algorithm to get an optimal diversity coloring on a tree. Note that for general graphs, an optimal diversity coloring might have $N > K$. For example, if the graph $G(V, E)$ is a ring with no less than $2m + 1$ vertices and $K = 2m + 1$, then we can prove that an optimal diversity coloring on the ring has $N = K + \lceil \frac{|V| \bmod K}{\lfloor \frac{|V|}{K} \rfloor} \rceil$, which is greater than K when $|V|$ is not a multiple of K . And actually when $K \geq m + 2 \geq 3$, for any arbitrarily large integer M ($M \geq K$), we can show that there exist graphs for which an optimal diversity coloring exists only if $N \geq M$. For more details of this paper, please refer to [2].

REFERENCES

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